

MarSurf

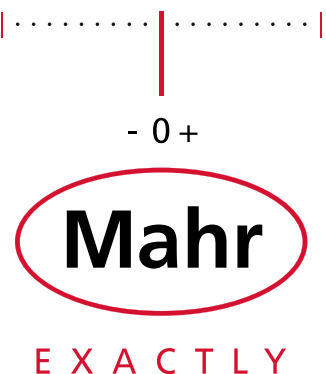


MarSurf LD 130 / 260 Aspheric

**HIGH-PRECISION 2D/3D MEASURING STATION FOR
MEASUREMENT AND EVALUATION OF OPTICAL
COMPONENTS**

- Measuring range 130 mm or 260 mm and more with stitching option
- High measuring speed
- Chip-coded innovative probe arms

This is what we mean by EXACTLY.



ASPHERE - DEFINITION

An aspherical surface is a refracting or reflecting surface which deviates from a spherical surface. The mathematical description of the sagitta z (dependance of the vertical height to the horizontal coordinates) of aspherical surfaces based on a conical section is given in the following equation:

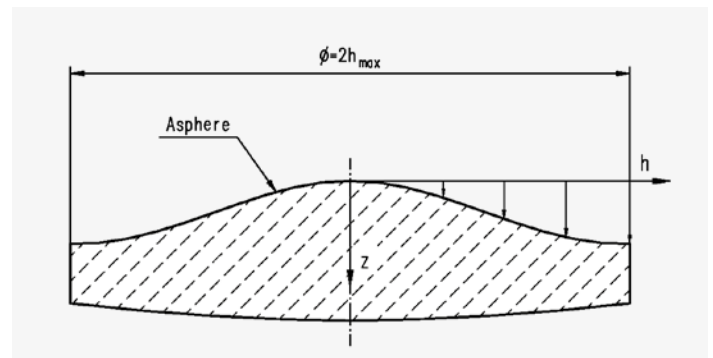
$$z(h) = \frac{\frac{h^2}{R_0}}{1 + \sqrt{1 - (1 + k) \cdot \left(\frac{h}{R_0}\right)^2}} + \sum_{n=1}^m A_n \cdot h^n$$

R_0 = Radius of curvature

h = Radius of interest

k = Conic constant

A_n = Aspherical coefficients



More info and videos.

www.mahr.com Webcode 21880

DESCRIPTION

An increasingly more compact and favorable system design is demanded on optical systems such as zoom lenses, optics for DVD drives and lenses in cameras of mobile phones, for example. For this purpose, in addition to classic spherical lens shapes, the optics industry is increasingly producing aspherical (not sphere-shaped) lenses. The evaluation program serves to analyze measurements on aspherical surfaces with Mahr contour measuring units. Measured profiles are imported, the nominal form of the aspheres are defined and the residual error is determined compared to the nominal form. The data of the determined differential profile is made available in a machine-readable format for correction of the processing machine (closed loop). In comparison to a laser interferometer, the tactile measuring technology also allows 2D and 3D measurement of optically rough surfaces, so that testing and correction is already possible in the beginning of the production process (grinding).



APPLICATIONS IN OPTICAL INDUSTRY

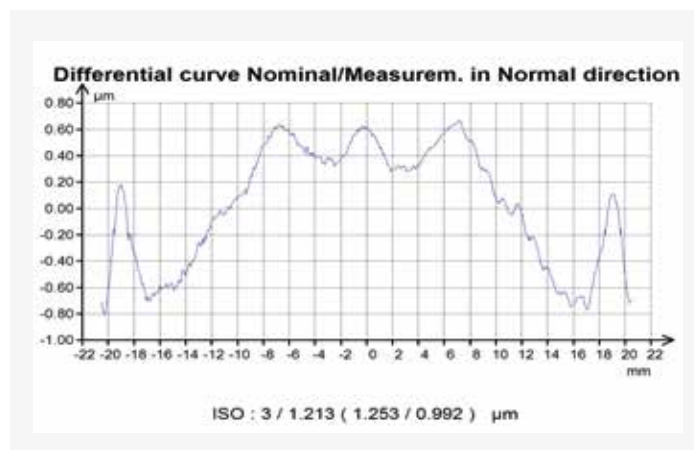
Contour and roughness measurement of:

- spherical and aspherical lenses
- cylinder lenses
- lens mounts
- housing and other mechanical components



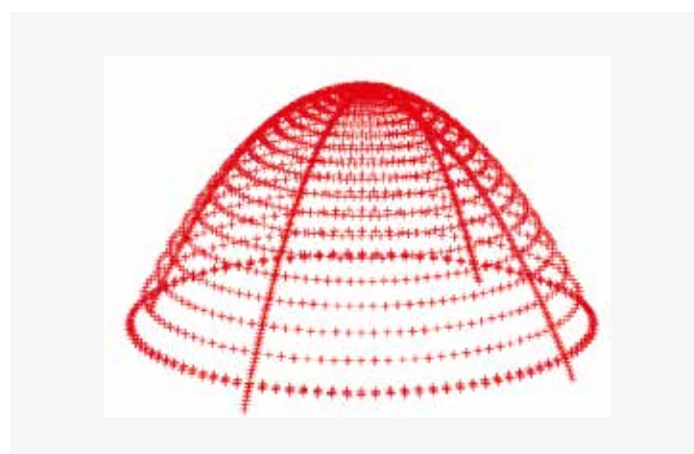
2D MEASUREMENT

- For the 2D measurement, a linear scan over the zenith of the asphere is performed
- Data collection of the aspherical contour
- Comparison of the nominal contour with the measured data
- Results according to DIN ISO 10110-5 (e.g. PV, RMS, slope error)
- Export of the differential profile to manufacturing machines (closed loop)



3D MEASURING PRINCIPLE

For a 3D measurement, two 90° offset linear profiles are first measured across the zenith of the asphere. Second, several concentric circular profiles are gathered by rotating the C-axis. These measured points are used to create the topography. Since the probe arms can be positioned automatically, it is possible to measure discontinuous surfaces such as optics with a hole in the center, for example. The use of the machine in a vibration-damped cabinet keeps ambient influences such as vibrations and impurities away from the measuring object.



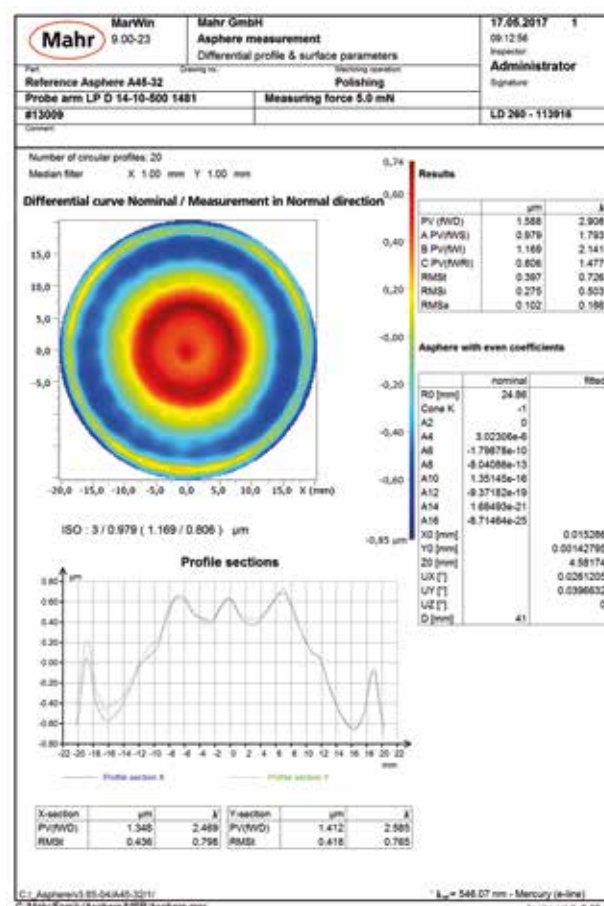
3D MEASUREMENT

Before starting the measurement, the nominal form type and set of parameters of the expected nominal asphere are selected. In the next step, the measuring data is recorded and compared to the defined nominal asphere. Results such as RMS value, PV value, and slope error are shown according to DIN ISO 10110-5.

In the software, the individual parameters such as the radius of curvature RO , conic constant k and the aspherical coefficients A_i can be adjusted to the measuring values when fitting the nominal asphere into the fit asphere.

In addition to spheres and aspheres, other rotationally symmetric objects can be measured and analyzed. For the nominal shape, several equations and a 2D or 3D point cloud can be used. The 2D scans and the topography can be exported for corrections in production machines.

The differential profile between the determined measuring values and the nominal asphere is shown as a color-coded height picture.

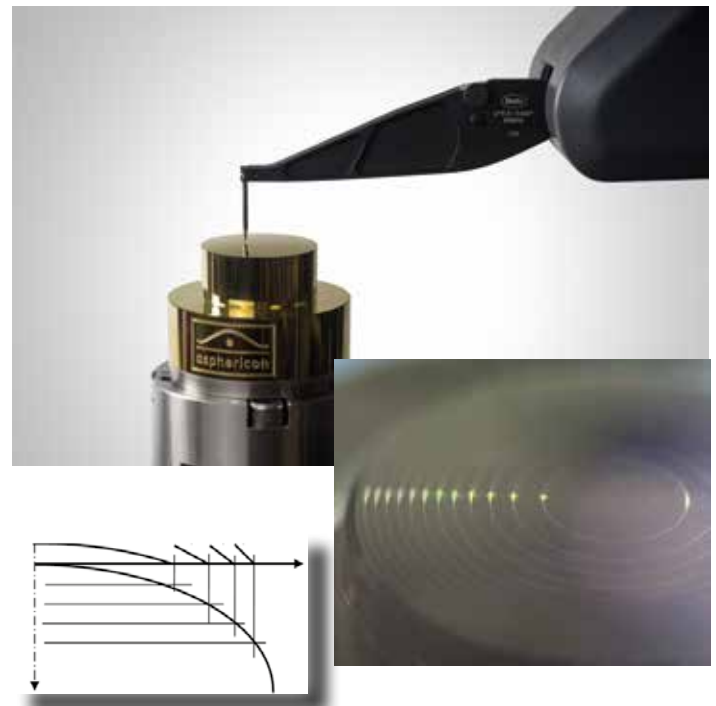


MEASUREMENT OF DIFFRACTIVE OPTICS

Description

- Analysis with constant zone width or constant zone height
- Analysis and subtraction of the base shape (aspherical, spherical, plane)
- Output parameters with tolerances for each zone: angle, zone height, form deviation and much more
- Profile export for machine correction

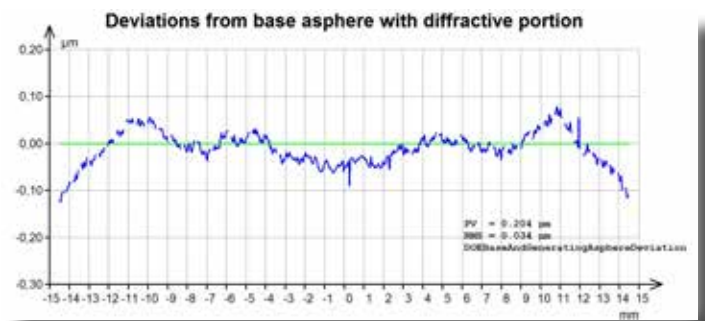
Diffractive structure with base shape removed



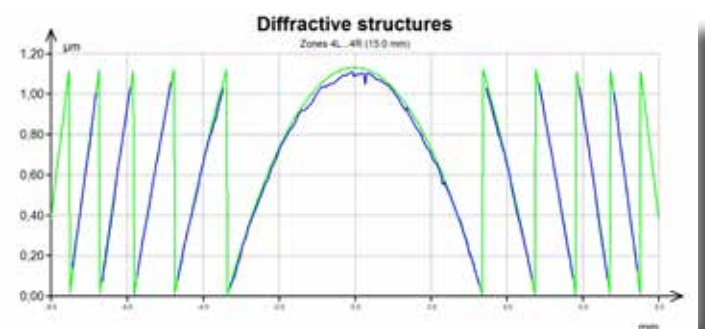
Profile for machine correcting

Detailed evaluation of each zone with tolerances (e.g. zone height)

Mahr		MarWin		Mahr GmbH		05.05.2017 3	
9.00.21		Asphere measurement		15.40.56		Inspector	
Reference DOE		Probe arm LP R 21-10-5_47 1123		Measuring force 0.5 mN		Administrator	
LD 260 - 116215						Signature:	
Height	Zone	Retained zone (µm)	UT (µm)	LT (µm)	Actual zone (µm)	Deviation (µm)	
DOE_0_R_0.0	0.0	0.000	0.000	-0.000	0.000	0.000	
DOE_10_R_4.7	4.7	0.000	0.000	-0.000	0.000	-0.000	
DOE_10_R_4.7	4.7	0.000	0.000	-0.000	0.000	-0.000	
DOE_21_R_5.7	5.7	0.000	0.000	-0.000	0.000	0.000	
DOE_21_R_5.7	5.7	0.000	0.000	-0.000	0.000	0.000	
DOE_32_R_6.8	6.8	0.000	0.000	-0.000	0.000	0.000	
DOE_32_R_6.8	6.8	0.000	0.000	-0.000	0.000	0.000	
DOE_43_R_7.9	7.9	0.000	0.000	-0.000	0.000	0.000	
DOE_43_R_7.9	7.9	0.000	0.000	-0.000	0.000	0.000	
DOE_54_R_9.0	9.0	0.000	0.000	-0.000	0.000	0.000	
DOE_54_R_9.0	9.0	0.000	0.000	-0.000	0.000	0.000	
DOE_65_R_10.1	10.1	0.000	0.000	-0.000	0.000	0.000	
DOE_65_R_10.1	10.1	0.000	0.000	-0.000	0.000	0.000	
DOE_76_R_11.2	11.2	0.000	0.000	-0.000	0.000	0.000	
DOE_76_R_11.2	11.2	0.000	0.000	-0.000	0.000	0.000	
DOE_87_R_12.3	12.3	0.000	0.000	-0.000	0.000	0.000	
DOE_87_R_12.3	12.3	0.000	0.000	-0.000	0.000	0.000	
DOE_98_R_13.4	13.4	0.000	0.000	-0.000	0.000	0.000	
DOE_98_R_13.4	13.4	0.000	0.000	-0.000	0.000	0.000	
DOE_109_R_14.5	14.5	0.000	0.000	-0.000	0.000	0.000	
DOE_109_R_14.5	14.5	0.000	0.000	-0.000	0.000	0.000	
DOE_120_R_15.6	15.6	0.000	0.000	-0.000	0.000	0.000	
DOE_120_R_15.6	15.6	0.000	0.000	-0.000	0.000	0.000	
DOE_131_R_16.7	16.7	0.000	0.000	-0.000	0.000	0.000	
DOE_131_R_16.7	16.7	0.000	0.000	-0.000	0.000	0.000	
DOE_142_R_17.8	17.8	0.000	0.000	-0.000	0.000	0.000	
DOE_142_R_17.8	17.8	0.000	0.000	-0.000	0.000	0.000	
DOE_153_R_18.9	18.9	0.000	0.000	-0.000	0.000	0.000	
DOE_153_R_18.9	18.9	0.000	0.000	-0.000	0.000	0.000	
DOE_164_R_20.0	20.0	0.000	0.000	-0.000	0.000	0.000	
DOE_164_R_20.0	20.0	0.000	0.000	-0.000	0.000	0.000	
DOE_175_R_21.1	21.1	0.000	0.000	-0.000	0.000	0.000	
DOE_175_R_21.1	21.1	0.000	0.000	-0.000	0.000	0.000	
DOE_186_R_22.2	22.2	0.000	0.000	-0.000	0.000	0.000	
DOE_186_R_22.2	22.2	0.000	0.000	-0.000	0.000	0.000	
DOE_197_R_23.3	23.3	0.000	0.000	-0.000	0.000	0.000	
DOE_197_R_23.3	23.3	0.000	0.000	-0.000	0.000	0.000	
DOE_208_R_24.4	24.4	0.000	0.000	-0.000	0.000	0.000	
DOE_208_R_24.4	24.4	0.000	0.000	-0.000	0.000	0.000	
DOE_219_R_25.5	25.5	0.000	0.000	-0.000	0.000	0.000	
DOE_219_R_25.5	25.5	0.000	0.000	-0.000	0.000	0.000	
DOE_230_R_26.6	26.6	0.000	0.000	-0.000	0.000	0.000	
DOE_230_R_26.6	26.6	0.000	0.000	-0.000	0.000	0.000	
DOE_241_R_27.7	27.7	0.000	0.000	-0.000	0.000	0.000	
DOE_241_R_27.7	27.7	0.000	0.000	-0.000	0.000	0.000	
DOE_252_R_28.8	28.8	0.000	0.000	-0.000	0.000	0.000	
DOE_252_R_28.8	28.8	0.000	0.000	-0.000	0.000	0.000	
DOE_263_R_29.9	29.9	0.000	0.000	-0.000	0.000	0.000	
DOE_263_R_29.9	29.9	0.000	0.000	-0.000	0.000	0.000	
DOE_274_R_31.0	31.0	0.000	0.000	-0.000	0.000	0.000	
DOE_274_R_31.0	31.0	0.000	0.000	-0.000	0.000	0.000	
DOE_285_R_32.1	32.1	0.000	0.000	-0.000	0.000	0.000	
DOE_285_R_32.1	32.1	0.000	0.000	-0.000	0.000	0.000	
DOE_296_R_33.2	33.2	0.000	0.000	-0.000	0.000	0.000	
DOE_296_R_33.2	33.2	0.000	0.000	-0.000	0.000	0.000	



Detailed view



ADVANTAGES

Checking topography during the first machining operations

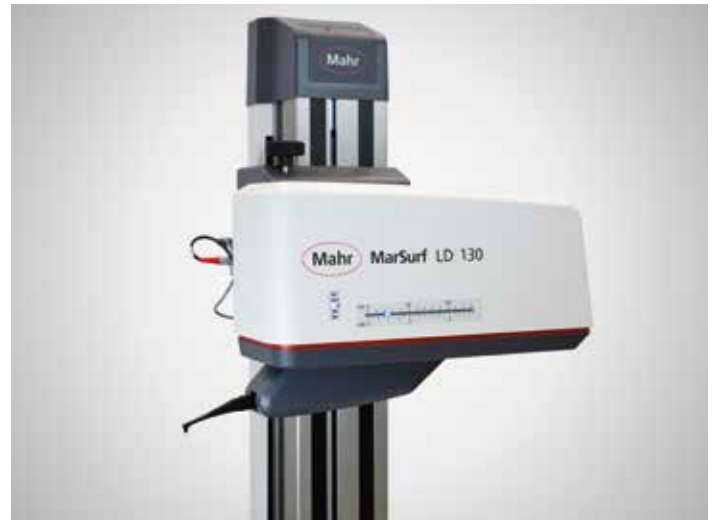
- Early recognition of deviations - saves time-consuming corrections
- Output of differential profile in a machine-readable format for control of the processing machine (closed loop)

Increased flexibility

- Rotational-symmetric objects like spheres, aspheres, conics, etc. can be measured with one measuring system. No additional investments are necessary.
- Large measuring range up to 260 mm (option: stitching)
- High measuring speed and dynamics (up to 10 mm/s for large lenses / down to 0.02 mm/s for micro lenses)
- Probe tip can be positioned automatically

Probe arm LP D with innovative design

- Higher dynamics due to increased stiffness, damping and lower moment of inertia:
 - Optimized mechanical design
 - Innovative material selection
- Probe arm with integrated chip:
 - Detection and identification of the probe arm
 - Verification of the correct mounting position
 - Probe arm provides its parameters directly



Your results are correct

- The highly precise MarSurf LD 130 / 260 is the basis for precision measurements of your workpieces. The vertical resolution of 0.8 nm (0.03 μin) and form deviations of less than 100 nm (4 μin) guarantee an exact production of your aspheres.
- Probe arm change without new calibration
- Measurement of steep sided aspheres possible

CALIBRATION SET FOR FIXTURE DIAMETER 25 MM

Consisting of:

- 2 cylinder for set up
- Calibration sphere
- Optical flat

Calibration Set for:

- Stylus calibration and system test
- System adjustment, cylinder with centered ball for chuck adjustment and stylus centering
- Application with automatic calibration and adjustment programs



SOFTWARE SOLUTION: ASPHERIC.LIB

- Analysis of form and contour errors of 2D or 3D measurements, including parameters according to DIN ISO 101105-5
- Automatic PDF record, including evaluation parameters and profiles
- System adjustment
- Automatic measurement
- Fit measured profile to design data (2D and 3D), best-fit radius, sag table
- Derive aspheric coefficients
- Profile export for machine correction (*.txt, *.mod, *.xyz, *.dat, *.ascii, *.x3p)

Option: Stitching

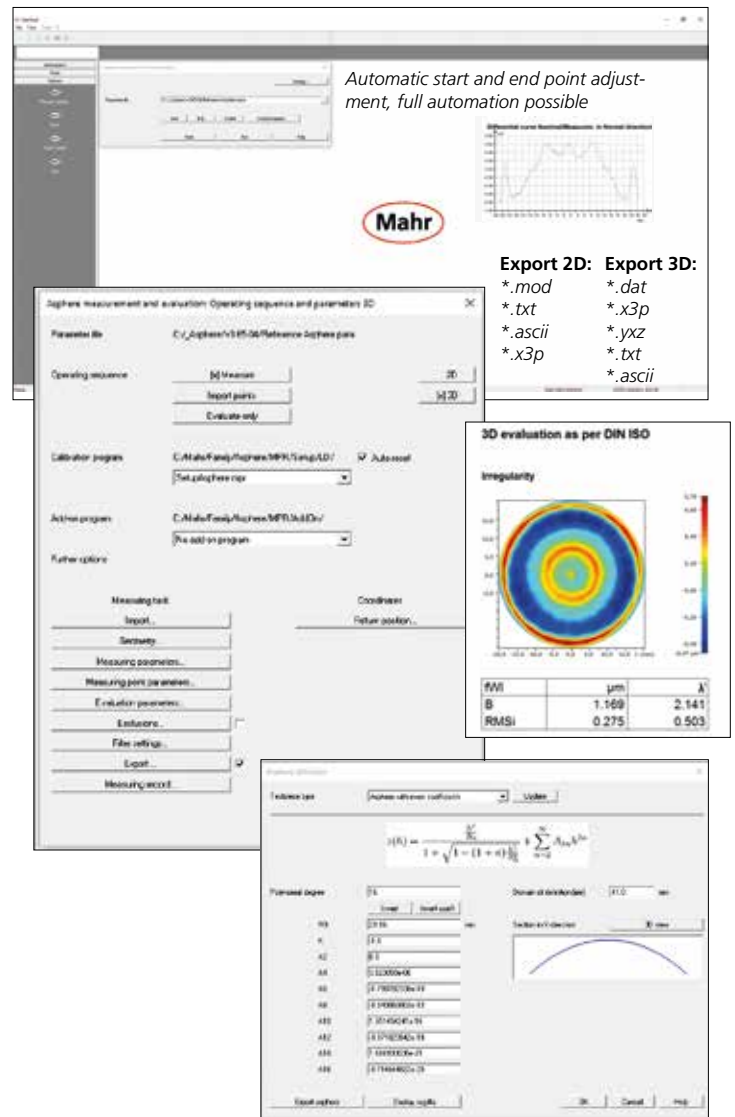
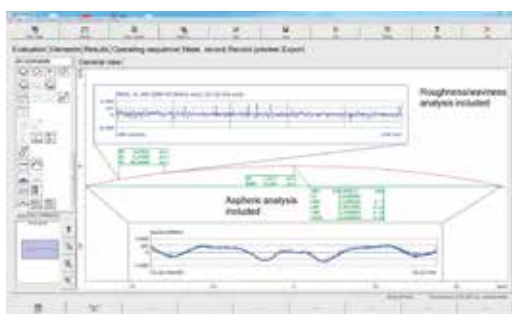
- Stitching of 2 or 3 linear profiles
- For applications:
 - large diameters
 - steep sided aspheres up to 75° with tilting table
 - aspheres with high sag values
- Tilting of workpiece possible
- Concave and convex

Option: Diffractive opticle Elements

- Analysis with constant zone width or constant zone height
- Analysis of the base shape (aspherical, spherical, plane)
- Detailed analysis of the diffractive zones
- Differential form error analysis
- Output parameters with tolerances (errors) for each zone: angle zone height, form deviation, zone half diameter
- Profile export for machine correction

MARWIN EASYCONTOUR WITH OPTIONS

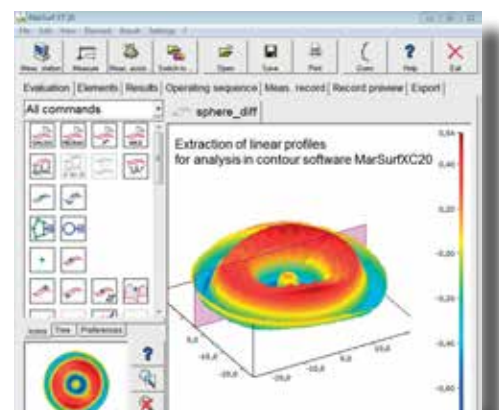
- Asphere measurments included
- Roughness and waviness analysis
- Profile analysis
- Parameters with tolerances



Aspheric.lib - Aspheric measuring and analysis software

OPTION TOPOGRAPHY

- Measurement and evaluation of 3D surface parameters
- Extraction of linear profiles for evaluation in the MarWin EasyContour software.



TECHNICAL DATA

Properties of the horizontal axis X

Traversing length	0.1 mm up to 130 mm / 260 mm
Positioning speed	0.02 mm/s up to 200 mm/s
Measuring speed	0.02 mm/s to 10 mm/s for roughness measurement recommended: 0.1 mm/s to 0.5 mm/s
Measuring point spacing	0.05 µm up to 30 µm, adjustable
Max number of points in one scan	2.6 million points (MarSurf LD 130) / 5.2 million points (MarSurf LD 260)
Resolution	0.8 nm (0.03 µin)
Uncertainty X-axis display	$\pm (0.2 + l/1000) \mu\text{m}$; l in mm
System noise	< 5 nm RMS
Surface roughness	< 5 nm

Technical data probe system (Measuring direction Z+ / Z-)

Probe measuring range	13 mm (100 mm probe arm) 26 mm (200 mm probe arm)
Resolution	0.8 nm
Measuring force	0.5 mN up to 30 mN (electronically adjustable)

Contour - display deviation

Distance measurement EA	MPEEA = $\pm (1.0 + l/150) \mu\text{m}$, l in mm
Radius measurement R_K	
$R < 10 \text{ mm}$	$\text{MPE}_R = \pm 1.0 \mu\text{m}$
$10 \text{ mm} < R < 300 \text{ mm}$	$\text{MPE}_R = \pm (0.17 + R/12) \mu\text{m}$
$R > 300 \text{ mm}$	$\text{MPE}_R = \pm (-18 + R/7) \mu\text{m}$
Form error	$\leq 100 \text{ nm (2D)}^*$ $\leq 200 \text{ nm (3D)}^*$
Slope	$< \pm 45^\circ$

* determined at R 22.5 mm calibration ball

Real 3D Measurement

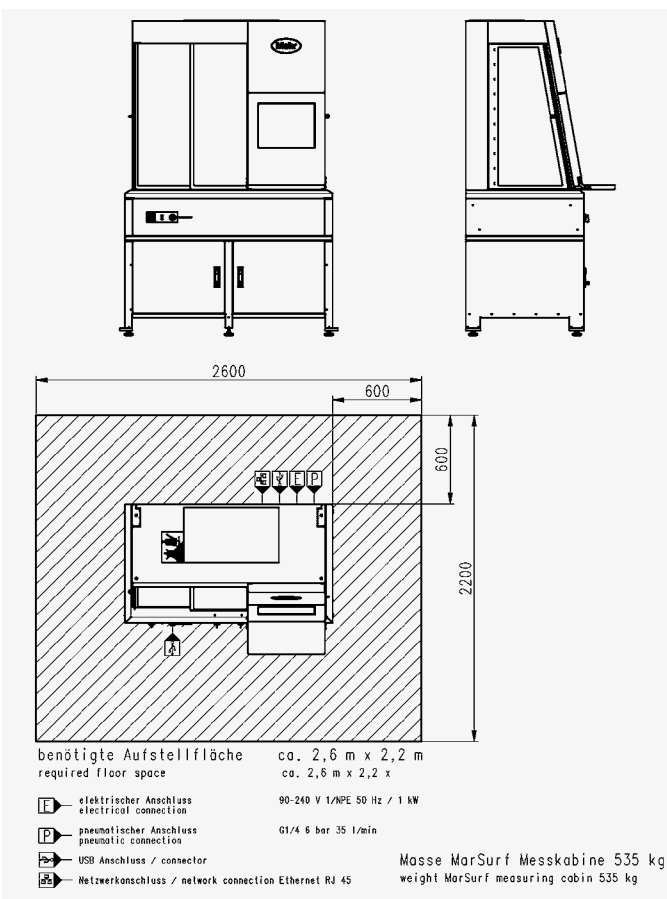
Measuring time	typically 5 to 10 min
Point density	typically: 1 µm linear, 0.1° polar 3D: Number of polar traces + interpolation
Drive unit with automatic y-axis for centering	

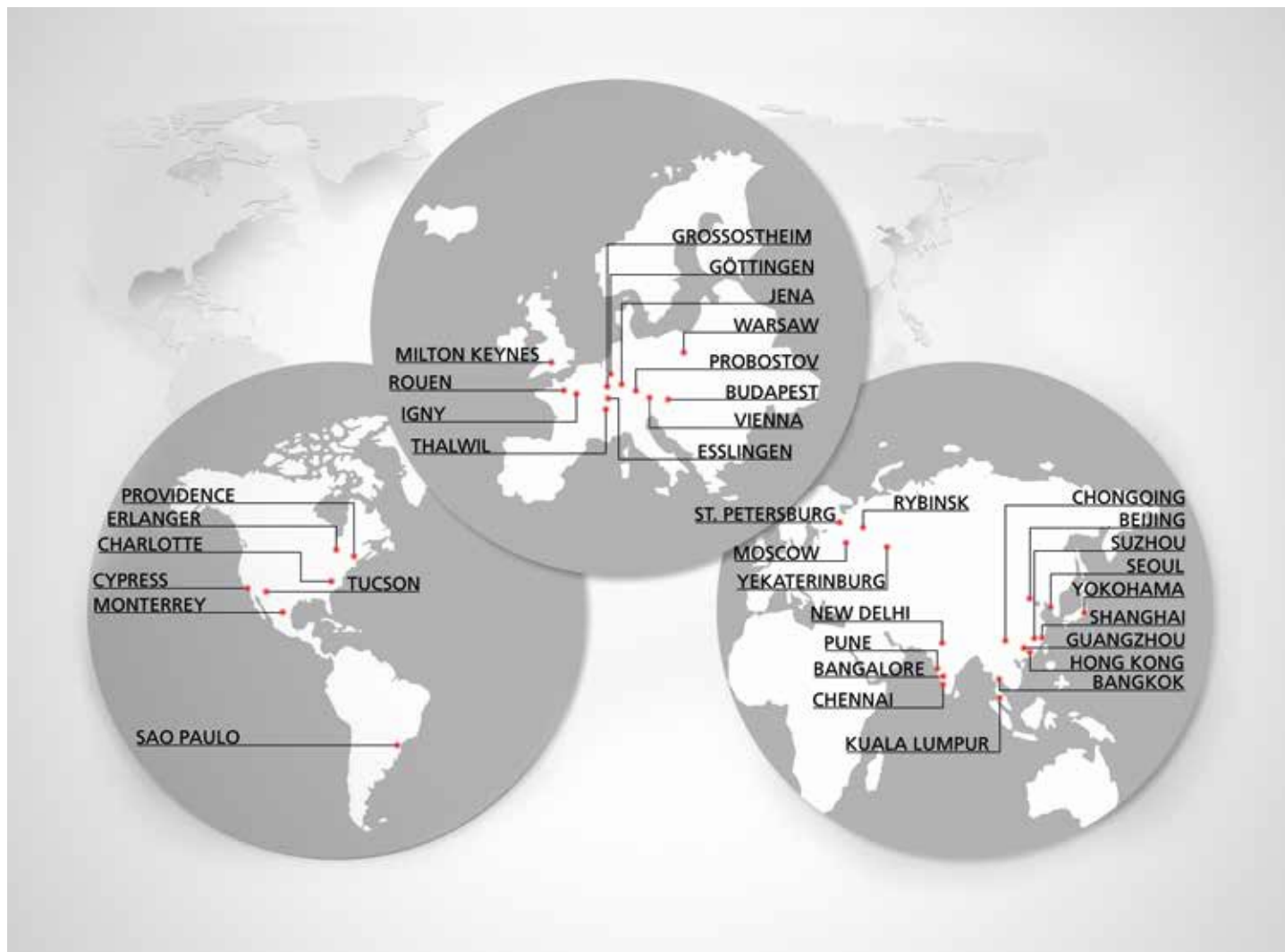
General Data

Operating temperature	+ 15°C to + 35°C
Suggested working temperature	20°C $\pm$ 2K
Temperature change	< 0.5 K/h
Active antivibration system	

High precision spindle (3D version)

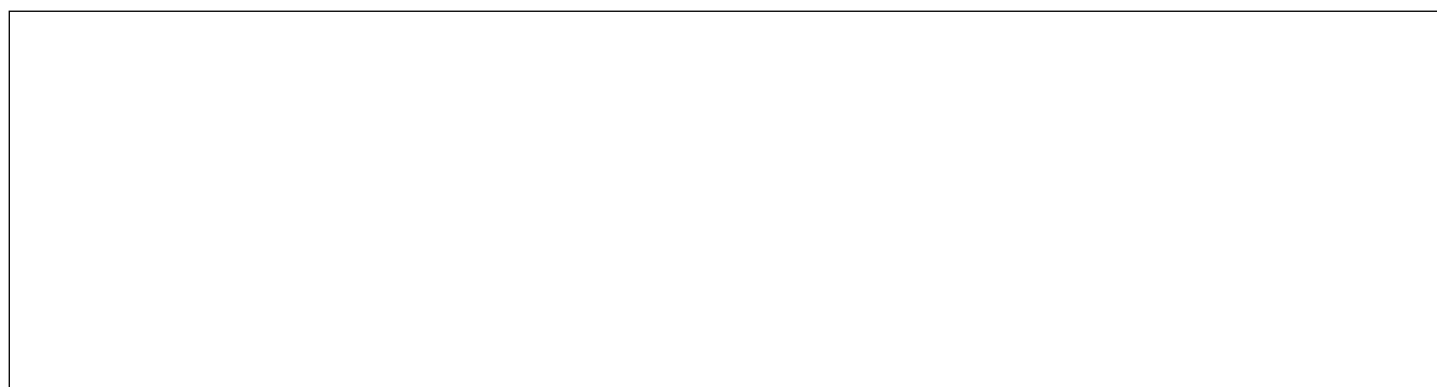
Radial error limit	$\pm (0.01 + 0.00025H) \mu\text{m}$; H = height above table
Axial error limit	$\pm (0.02 + 0.0001R) \mu\text{m}$; R = radius form center
Resolution	0.00025°
Positioning control	$< \pm 0.02^\circ$
Accuracy precision centering	< 0.8 µm
Accuracy precision levelling	< 0.006°





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Close to our customers.



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EXACTLY